



Hopf and Marcus-Wyse Topologies on \mathbb{Z}^2

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Received: 1st November 2016

Accepted: 12th April 2017

ABSTRACT

The two conditions 1^2 and 2^2 are so that any digital topology on \mathbb{Z}^2 satisfies them is topologically connected whenever it is graphically connected. In this paper, we show that the two digital topologies on \mathbb{Z}^2 satisfy 1^2 and 2^2 are precisely the Hopf and the Marcus-Wyse Topologies. We prove that the Hopf topology is the product of two Khalimsky topologies on \mathbb{Z} . We also prove that the Hopf topology is homeomorphic to the cellular-complex topology on \mathbb{F}^2 while the Marcus-Wyes topology is homeomorphic to $\mathbb{F}_{\{0,2\}}^2$.

Keywords: Digital spaces, Alexandroff spaces, Hopf topology, Marcus-Wyes topology, cellular-complex topology.

1. Introduction and Preliminaries

For a topological space (X, τ) , a subset A is called a *semi-open* in Levine (1963) (resp. a *preopen* (Mashhour et al. (1982)), an α -*open* (Njastad (1965))) if $A \subseteq \overline{A^\circ}$ (resp. $A \subseteq \overline{A}^\circ$, $A \subseteq \overline{A^\circ}$). It is called a *semi-closed* set Crossley and Hildebrand (1971) (resp. a *preclosed* set in El-Deep et al. (1983)), an α -*closed* in Dontchev (1998a) if A^c is semi-open (resp. preopen, α -open).

We denote $SO(X)$ (resp. τ_α , $PO(X)$) to be the family of all semi-open (resp. α -open, preopen) sets in X .

A topological space X is called a *semi- T_o* in Maheshwari and Prasad (1975) (resp. an α - *T_o* in Maki et al. (1993), a *pre- T_o*)-space if whenever x and y are distinct points in X , there is a semi-open (resp. an α -open, a pre-open) set which contains one of x, y and not the other.

X is $T_{\frac{1}{4}}$ in Arenas et al. (1997) (resp. $T_{\frac{1}{3}}$ in Arenas et al. (2000))-space if for every finite (resp. compact) subset F of X and every $y \notin F$, there exists a set A_y containing F and disjoint from $\{y\}$ such that A_y is either open or closed. X is $T_{\frac{1}{2}}$ in Dunham (1977) (resp. $T_{\frac{3}{4}}$ in Dontchev (1998b), *semi- $T_{\frac{1}{2}}$* in Cueva and Saraf (2000), α - $T_{\frac{1}{2}}$, a *feebly T_1* (Jankovic and Reilly (1985)), a *semi- T_D* in Jankovic and Reilly (1985)) if every singleton is either open (resp. regular open, semi-open, α -open, nowhere dense, open) or closed (resp. closed, semi-closed, α -closed, clopen, nowhere dense). X is *semi- T_1* in Maheshwari and Prasad (1975) (resp. α - T_1 in Maki et al. (1993)) if every singleton is semi-closed (resp. α -closed) set. X is T_1^* -*space* Ganster et al. (1992) if every nowhere dense subset of X is union of closed sets. X is a *submaximal space* (Reilly and Vamanamurthy (1990)) if every dense subset is open, or equivalently every preopen subset is open. A *nodec space* in Van Mill and Mills (1980) is a space where all nowhere dense sets are closed. A *locally finite* space X is a space such that for any element $x \in X$ there exists a finite open set U_x such that $x \in U_x$.

For a given poset (X, \leq) , we define M to be the set of all maximal elements and the set m to be the set of minimal elements in X .

For $x \in X$ we define the down set $\downarrow x := \{y \in X : y \leq x\}$ and the up set $\uparrow x := \{y \in X : y \geq x\}$. For a point $x \in X$, we define $\hat{x} = \uparrow x \cap M$. A poset X satisfies the *ascending chain conditions*, (*ACC*) if any increasing sequence is finally constant. A poset X satisfies the *descending chain conditions*, (*DCC*) if any decreasing sequence is finally constant. If X satisfies *ACC* (resp. *DCC*), then the set M (resp. m) is nonempty set. There is a very useful way to depict

posets using the so called *Hasse diagrams*.

For posets (P_i, \leq_i) , $i = 1, 2, \dots, n$, we can formulate many types of partial orders the cartesian product $\prod_i^n P_i = P_1 \times P_2 \cdots \times P_n$. The most famous order is the *coordinatewise order* \leq_c . For two elements $a = (a_1, a_2, \dots, a_n)$ and $b = (b_1, b_2, \dots, b_n)$ in $\prod_i^n P_i$, we have that $a \leq_c b$ iff $a_i \leq_i b_i \forall i = 1, 2, \dots, n$.

A topological space X is called an *Alexandroff space* (In short, A -space) if the intersection of any collection of open sets is open. Equivalently, any element x in X has a minimal neighborhood base $V(x)$ which is the intersection of all open sets containing x . If X is an A -space and $x, y \in X$, then $x \in \overline{\{y\}}$ if and only if $y \in V(x)$.

If an A -space (X, τ) is T_0 , then we define a (*Alexandroff*) *specialization order* as $a \leq_\tau b$ if $a \in \overline{\{b\}}$, (equivalently $b \in V(a)$). If (X, \leq) is a poset, then the collection $\mathfrak{B} = \{\uparrow x : x \in X\}$ is a base for a T_0 A -topology on X denoted by τ_\leq .

From now on, we denote $(X, \tau(\leq))$ to be a T_0 A -space (X, τ) where (X, \leq) is its corresponding poset. If $(X, \tau(\leq))$ is a T_0 A -space, then $\forall x \in X$, $V(x)$ equals $\uparrow x$. If (X, τ) is an A -space with the collection \mathcal{F} of closed sets, then \mathcal{F} is itself an Alexandroff topology on X called *the dual* of τ on X and usually denoted by τ^d . If $(X, \tau(\leq))$ is a T_0 A -space, then the Alexandroff dual is also T_0 -space, and the induced order \leq_a is the reverse order of the order \leq ; that is $x \leq_a y$ iff $y \leq x$.

Thus, for $x \in X$, we have $V(x) = cl_a(x)$ and $V_a(x) = cl(x)$. Two distinct points x and y in X are called *adjacent* if the subspace $\{x, y\}$ is (topologically) connected.

Definition 1.1. (*Mahdi and EL-Mabhouh (2011)*). A T_0 A -space $(X, \tau(\leq))$ is called *Artinian* (resp. *Noetherian*) *Mahdi and Elatrash (2005)* if the corresponding poset satisfies the *ACC* (resp. *DCC*). If a T_0 A -space is both Artinian and Noetherian, then it is called a *generalized locally finite* (*g-locally finite*).

Theorem 1.2. (*Mahdi (2015)*). Let X and Y be two T_0 A -spaces. Then X and Y are homeomorphic iff there exists a bijective function $f : X \rightarrow Y$ such that $f(V_X(x)) = V_Y(f(x))$, $\forall x \in X$.

Theorem 1.3. (*Mahdi and Elatrash (2006)*). Let X be a T_0 A -space. Then all the following are equivalent:

- (i) X is $T_{\frac{1}{2}}$ -space.
- (ii) X is $T_{\frac{1}{3}}$ -space.

- (iii) X is $T_{\frac{1}{4}}$ -space.
- (iv) Each element of X is either open or closed. Equivalently, the elements in the corresponding poset is either minimal or maximal.
- (v) X is submaximal.
- (vi) $PO(X) = \tau_\alpha = \tau(\leq)$; that is, every preopen set is open.
- (vii) X is T_1^* -space.

Theorem 1.4. (Mahdi and Elatrash (2006)). Let X be a T_0 A -space. Then X is $T_{\frac{3}{4}}$ iff the following two conditions are satisfied:

- (a) X is $T_{\frac{1}{2}}$ -space.
- (b) $\forall x \notin M, |\hat{x}| \geq 2$; where $|\hat{x}|$ is the cardinality of the set \hat{x} .

Theorem 1.5. (Mahdi and Elatrash (2006)). Let X be an Artinian T_0 A -space. Then X is both α - $T_{\frac{1}{2}}$ -space and semi- $T_{\frac{1}{2}}$ -space.

Theorem 1.6. (Mahdi and Elatrash (2006)). If X is an Artinian T_0 A -space, then the following statements are equivalent:

- (1) X is a semi- T_2 -space.
- (2) X is a semi- T_1 -space.
- (3) $\forall x \notin M, |\hat{x}| \geq 2$.

Theorem 1.7. (Mahdi (2010)). If $(X, \tau_x(\leq_x))$ and $(Y, \tau_y(\leq_y))$ are two T_0 A -spaces with corresponding posets (X, \leq_x) , (Y, \leq_y) respectively, then $X \times Y$ is a T_0 A -space induces a specialization order \leq_p coincides with the coordinatewise order of the product of the corresponding posets.

2. Properties of Digital Spaces on \mathbb{Z}^2

The digital space \mathbb{Z}^2 is the set of all tuples (x_1, x_2) of the Euclidean space having integer coordinates. Let $a = (a_1, a_2), b = (b_1, b_2) \in \mathbb{Z}^2$. The length of the i 'th coordinate between a and b is $r_i(a, b) = |a_i - b_i|$, and the total coordinates length between a and b is $R(a, b) = |a_1 - b_1| + |a_2 - b_2|$. For a given point $x \in \mathbb{Z}^2$, the 8-neighborhood $N_8(x)$ of x is the set of all points $y \in \mathbb{Z}^2$ such that $x \neq y$ and $r_i(x, y) \leq 1$ for $i = 1, 2$. The elements in $N_8(x)$ are called 8-neighbors (or 8-adjacent) of x . The 4-neighborhood $N_4(x)$ of x is the set of all points $y \in \mathbb{Z}^d$ such that $R(x, y) = 1$. The elements in $N_4(x)$ are called 4-neighbors (or 4-adjacent) of x . An n -path ($n = 4, 8$) from x to y is a list of elements $x = x_1, x_2, \dots, x_k = y$ satisfy that for $1 < i \leq k, x_i$ is n -adjacent of x_{i-1} . Let $X \subseteq \mathbb{Z}^2$. For $n = 4, 8$ if for each points $x, y \in X$, there is n -path contained in X from x to y , X is called n -connected. Eckhardt and Latecki (2003) suggest the following two conditions so that any topology on \mathbb{Z}^2 satisfies these conditions will be topologically connected whenever it is graphically connected:

- (1²) If a set in \mathbb{Z}^2 is 4-connected, then it is topologically connected.
- (2²) If a set in \mathbb{Z}^2 is not 8-connected, then it is not topologically connected.

Henceforth, we will consider the digital topology on \mathbb{Z}^2 to mean any topology satisfying 1² and 2². In Mahdi and Hegazy (2016) we proved that there are only two digital topologies τ_s and τ_m on \mathbb{Z}^2 , which are g -locally finite T_0 A -spaces. With respect to any digital topology on \mathbb{Z}^2 , if $x, y \in \mathbb{Z}^2$, define $x \rightarrow y$ (or $y \leftarrow x$) if for each open set U containing x , we have $y \in U$.

The notation $x \rightarrow y$ denotes the negation of $x \rightarrow y$ Eckhardt and Latecki (2003). the relation " \rightarrow " is a partial order on \mathbb{Z}^2 . With respect to this order, a point $x \in \mathbb{Z}^2$ is called a *saddle point* (Eckhardt and Latecki (2003)) if it is neither maximal nor minimal points. The set of all saddle points is denoted by SD . We prove that (\mathbb{Z}^2, τ_s) contains saddle points, while (\mathbb{Z}^2, τ_m) has no saddle point.

Definition 2.1. (Mahdi and Hegazy (2016)). Define two subsets EV_2, OD_2 of \mathbb{Z}^2 as follows :

- (i) $EV_2 = \{(a, b) : a + b \text{ is even number}\}$.
- (ii) $OD_2 = \{(a, b) : a + b \text{ is odd number}\}$.

Theorem 2.2. (Mahdi and Hegazy (2016)). If x is a maximal (resp. a minimal, a saddle) point in \mathbb{Z}^2 , then no point in $N_4(x)$ is a maximal (resp. a minimal, a saddle) point.

Lemma 2.3. (Mahdi and Hegazy (2016)). In the digital space (\mathbb{Z}^2, τ_m) if x is a maximal (resp. a minimal) point, then all points in $N_8(x) \setminus N_4(x)$ are maximal (resp. minimal) points.

Theorem 2.4. (Mahdi and Hegazy (2016)). In the digital space (\mathbb{Z}^2, τ_m) , if $x \in X$ is a minimal point, then the minimal open set $V(x) = N_4(x) \cup \{x\}$.

Theorem 2.5. (Mahdi and Hegazy (2016)). Let τ_s be the digital topology on \mathbb{Z}^2 with saddle points and $x \in \mathbb{Z}^2$. Then:

- (1) if x is a maximal point or a minimal point, then $N_4(x)$ is a set of saddle points.
- (2) if x is a saddle point, then $\forall y \in N_4(x)$, y is either maximal or minimal point.

(3) if x is a maximal (resp. a minimal) point, then $\forall y \in N_8(x) \setminus N_4(x)$, y is a minimal (resp. a maximal) point.

(4) if x is a saddle point, then $\forall y \in N_8(x) \setminus N_4(x)$, y is a saddle point.

Theorem 2.6. (Mahdi and Hegazy (2016)). In the digital space (\mathbb{Z}^2, τ_s) with saddle points, if $x \in X$ is a minimal point, then the minimal open set $V(x) = N_8(x) \cup \{x\}$. if $y \in X$ is a saddle point, then the minimal open set $V(y) = (M \cap N_4(y)) \cup \{y\}$.

3. Marcus-Wyse Topology on \mathbb{Z}^2

The Marcus-Wyse topology is a special connected $T_{\frac{1}{2}}$ A -space on \mathbb{Z}^2 . This topology was described by Marcus and Wyse (1970). They defined this topology by its minimal neighbourhood as follows: for any point $x = (a, b) \in \mathbb{Z}^2$, $V(x) = \{x\} \cup N_4(x)$ if $a+b$ is even and $V(x) = \{x\}$ otherwise.

Hence the digital topology τ_m on \mathbb{Z}^2 is exactly the Marcus-Wyse topology. This topology is a T_0 A -space, and its specialization order is denoted by (\leq_m) . If $u \in EV_2$, then $N_4(u) \subseteq OD_2$ and $N_8(u) \setminus N_4(u) \subseteq EV_2$. If $u \in OD_2$, then $N_4(u) \subseteq EV_2$ and $N_8(u) \setminus N_4(u) \subseteq OD_2$. Moreover if $u, v \in EV_2$ (resp. OD_2), then there exists a finite sequence $u = u_0, u_1, u_2, \dots, u_n = v$ in EV_2 (resp. OD_2) such that $u_{i-1} \in N_8(u_i) \setminus N_4(u_i) \forall i = 1, 2, \dots, n$.

Theorem 3.1. Let (\mathbb{Z}^2, τ_m) be the Marcus-Wyse space. If there exists a minimal (resp. a maximal) point u such that $u \in EV_2$, then $EV_2 = m$ and $OD_2 = M$ (resp. $EV_2 = M$ and $OD_2 = m$).

Proof. Let $u \in EV_2 \cap m$ and $v \in EV_2$. Then there exists a finite sequence $u = u_0, u_1, \dots, u_n = v$ in EV_2 such that $u_{i-1} \in N_8(u_i) \setminus N_4(u_i)$, $i = 1, 2, \dots, n$. Hence v is a minimal point. Conversely, if $w = (a, b) \in OD_2$, then $(a + 1, b) \in EV_2$ and so $(a+1, b)$ is minimal point. By Theorem 2.2, w is maximal point. \square

Hence, in the Marcus-Wyse topology on \mathbb{Z}^2 , we have two possible cases: " $m = EV_2$ and $M = OD_2$ " or " $M = OD_2$ and $m = EV_2$ ". It is clearly that they are homeomorphic. By convention, we will take the topology in the first case to be the Marcus -Wyse topology (\mathbb{Z}^2, τ_m) and the topology τ_m^d in the second case will be its homeomorphic dual. The up of a point $x \in \mathbb{Z}^2$ in τ_m is denoted by $\uparrow_m x$ and in τ_m^d by $\uparrow_m^d x$.

Using a net diagram in (a) or a Hasse diagram in (b) a part of the Marcus-Wyse topology on \mathbb{Z}^2 is shown in Figure 1:

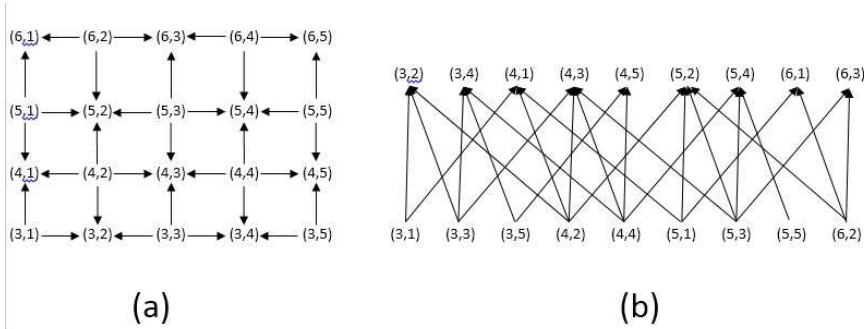


Figure 1: Part of Marcus-Wyse Topology on \mathbb{Z}^2

The specialization order of the Marcus-Wyse topology on \mathbb{Z}^2 denote by \leq_m . Using Lemma 2.4, if $x \in EV_2 = m$, then $\uparrow_m x = N_4(x) \cup \{x\}$ and if $x \in OD_2 = M$, then $\uparrow_m x = \{x\}$. Then we have the following theorem.

Theorem 3.2. *If x and y are two distinct points in \mathbb{Z}^2 , then $x \leq_m y$ iff $x \in EV_2$ and $y \in N_4(x)$.*

Theorem 3.3. *Let (\mathbb{Z}^2, τ_m) be the Marcus-Wyse topology on \mathbb{Z}^2 , then*

- (1) \mathbb{Z}^2 is submaximal.
- (2) \mathbb{Z}^2 is nodec.
- (3) $PO(\mathbb{Z}^2) = \tau_\alpha = \tau(\leq)$; that is, every preopen set is open.
- (4) \mathbb{Z}^2 is T_1^* -space.
- (5) \mathbb{Z}^2 is $T_{\frac{3}{4}}$.
- (6) \mathbb{Z}^2 is semi- T_2 -space.

Proof. Any element of \mathbb{Z} is either maximal or minimal, so by Theorem 1.3, we get the parts (1),(2),(3) and (4). Since \mathbb{Z} is submaximal, then by Theorem 1.3, it is $T_{\frac{1}{2}}$ -space. Moreover, since $|\hat{x}| = 2 \forall x \notin M$, by Theorem 1.4, \mathbb{Z} is $T_{\frac{3}{4}}$ -space. Part(6) is coming directly from Theorem 1.6. \square

4. Alexandroff Hopf Topology on \mathbb{Z}^2

In Eckhardt and Latecki (2003) said that the digital topology τ_s on \mathbb{Z}^2 which has saddle points (τ_s) is homeomorphic to the cellular-complex topology (Alexandroff Hopf topology). We will latter define a useful function and using it to prove this fact.

Let O and V be the odd and the even numbers in \mathbb{Z} respectively. We define the subsets of \mathbb{Z}^2 EE, OO, EO and OE as : $EE = E \times E, OO = O \times O, EO = E \times O$ and $OE = O \times E$. Hence $OD_2 = EO \cup OE$ and $EV_2 = EE \cup OO$.

Let \leq_s be the induced order on \mathbb{Z}^2 by the Hopf topology τ_s . The up of a point $x \in \mathbb{Z}^2$ in τ_s is denoted by \uparrow_s .

Lemma 4.1. *Let (\mathbb{Z}^2, τ_s) be the Hopf space and let $x, y \in \mathbb{Z}^2$.*

- (1) *If x is a maximal (resp. a minimal) point and if $r_1(x, y) = 2k_1$ and $r_2(x, y) = 2k_2$ for some integers k_1, k_2 , then y is a maximal (resp. a minimal) point.*
- (2) *If x is a saddle point and $R(x, y) = 2$, then y is a saddle point.*

Theorem 4.2. *Let (\mathbb{Z}^2, τ_s) be the Hopf space, and $u = (x, y) \in EE$.*

- (i) *If u is a minimal point, then $m = EE, M = OO$, and $SD = OD_2$.*
- (ii) *If u is a maximal point, then $m = OO, M = EE$, and $SD = OD_2$.*
- (iii) *If u is a saddle point, then $SD = EV_2$, and either " $M = OE$ and $m = EO$ " or " $M = EO$ and $m = OE$ ".*

Proof. (i) Let $(a, b) \in EE$. Then $a = x + 2s$ and $b = y + 2r$ for some integers s, r . Using the induction and Lemma 4.1, we have $(a, b) \in m$. Hence $EE \subseteq m$. If $(a, b) \in OO$, then $(a+1, b+1) \in EE \subseteq m$ and $(a+1, b+1) \in N_8(a, b) \setminus N_4(a, b)$. Hence $(a, b) \in M$ and so $OO \subseteq M$. If $(a, b) \in OD_2$, then $(a+1, b) \in EV_2 \subseteq m \cup M$. So $(a, b) \in SD$ and hence $OD_2 \subseteq SD$. Thus $m = EE, M = OO$, and $SD = EO \cup OE = OD_2$.

(ii) Similar to (i).

(iii) Let $(a, b) \in EE$. Similarly to (i), $EE \subseteq SD$. Assume that $(a, b) \in OO$. Hence $a = x + 2s + 1$ and $b = y + 2r + 1$ for some integers s, r . By Lemma

4.1, $(x + 2n, y + 2r) \in SD$ and so $(a, b) \in SD$. Therefore, $OO \subseteq SD$ and thus $EV_2 \subseteq SD$. Let $(a, b) \in OE$. Then $(a + 1, b) \in EV_2 \subseteq SD$. By Theorem 2.5, either $(a, b) \in M$ or $(a, b) \in m$. Hence $OE \subseteq M \cup m$. Assume that $OE \subseteq M$ (resp. $OE \subseteq m$). Let $(a, b) \in EO$. Then $(a + 1, b) \in SD$ and $(a, b) \notin SD$. Suppose to contrary that $(a, b) \in M$ (resp. $(a, b) \in m$). So $N_4(a + 1, b) \subseteq M$ (resp. $N_4(a + 1, b) \subseteq m$) which is a contradiction since $(a + 1, b) \in SD$. \square

Corollary 4.3. *Let (\mathbb{Z}^2, τ_s) be the Hopf space.*

- (a) *If $m = EE$, then $M = OO$ and $SD = EO \cup OE$.*
- (b) *If $m = EO$, then $M = OE$ and $SD = EE \cup OO$.*
- (c) *If $m = OE$, then $M = EO$ and $SD = EE \cup OO$.*
- (d) *If $m = OO$, then $M = EE$ and $SD = EO \cup OE$.*

Proof. (a) Direct from Theorem 4.2.

(b) Let $(x, y) \in EO$, then $(x, y + 1) \in SD \cap EE$. Hence $M = OE$, $SD = EE \cup OO$. Parts (c) and (d) are similar to (b). \square

It is clearly that if \mathbb{Z}^2 has the topology τ_s and $(x, y) \in \mathbb{Z}^2$, such that (x, y) is a maximal or a minimal point, then we can determine the type (maximal, minimal, or saddle) of any point in \mathbb{Z}^2 . Moreover, if (x, y) is a saddle point in \mathbb{Z}^2 , then we have at most two cases for any point in \mathbb{Z}^2 . In fact there exist four topologies in \mathbb{Z}^2 . All of them can be considered as a τ_s topology, and all of them are homeomorphic to each others. They are considered as one topology on \mathbb{Z}^2 . By convention, we will consider the Hopf topology to be such that $m = EE$, $M = OO$ and $SD = EO \cup OE$. The other three types of homeomorphic topologies on \mathbb{Z}^2 are also called Hopf topology on \mathbb{Z}^2 , but if we take any one of the three other types as the Hopf topology on \mathbb{Z}^2 , we must say so.

Theorem 4.4. *Let \mathbb{Z}^2 be the Hopf topology and $(a, b) \in \mathbb{Z}^2$.*

- (a) *If $(a, b) \in OO$, then $\uparrow(a, b) = \{(a, b)\} = \{a\} \times \{b\}$.*
- (b) *If $(a, b) \in EE$, then $\uparrow(a, b) = N_s(a, b) \cup \{(a, b)\} = \{a - 1, a, a + 1\} \times \{b - 1, b, b + 1\}$.*
- (c) *If $(a, b) \in EO$, then $\uparrow(a, b) = \{(a - 1, b), (a, b), (a + 1, b)\} = \{a - 1, a, a + 1\} \times \{b\}$.*

(d) If $(a, b) \in OE$, then $\uparrow(a, b) = \{(a, b - 1), (a, b), (a, b + 1)\} = \{a\} \times \{b - 1, b, b + 1\}$.

Definition 4.5. (Melin (2003)). The Khalimsky topology on the set of integer numbers \mathbb{Z} is a T_0 A -space where the smallest neighborhoods $V(i) = \{i\}$ if i is odd and $V(i) = \{i - 1, i, i + 1\}$ if i is even.

Definition 4.6. Let (\mathbb{Z}, τ_{kh}) be the Khalimsky space. The product of two Khalimsky spaces on \mathbb{Z}^2 denoted by τ_p which is T_0 A -space with minimal neighbourhood $\uparrow_{kh}(a, b) = \uparrow_{kh} a \times \uparrow_{kh} b$ for all $(a, b) \in \mathbb{Z}^2$.

Theorem 4.7. Let (\mathbb{Z}, τ_{kh}) be the Khalimsky space and (\mathbb{Z}^2, τ_s) be the Hopf space. Then $\mathbb{Z}^2 = \mathbb{Z} \times \mathbb{Z}$. That is $\tau_s = \tau_p$.

Proof. Firstly the two topologies τ_s and τ_p are T_0 A -spaces on \mathbb{Z}^2 . By Theorem 4.4, $\uparrow_p(a, b) = \uparrow_{kh} a \times \uparrow_{kh} b = \uparrow_s(a, b)$ for all $(a, b) \in \mathbb{Z}^2$. Hence by Theorem 1.7 and Theorem 1.2, $\tau_s = \tau_p$. \square

Remark 4.8. The other three homeomorphic types of the Hopf topologies are the product of $(\mathbb{Z}, \tau_{kh}) \times (\mathbb{Z}, \tau_{kh}^d)$, $(\mathbb{Z}, \tau_{kh}^d) \times (\mathbb{Z}, \tau_{kh})$ and $(\mathbb{Z}, \tau_{kh}^d) \times (\mathbb{Z}, \tau_{kh}^d)$. For example, in the Hopf topology $(\mathbb{Z}, \tau_{kh}^d) \times (\mathbb{Z}, \tau_{kh})$, $m = OE$.

Using a net diagram in (a) or a Hasse diagram in (b), a part of Hopf topology on \mathbb{Z}^2 looks like as in Figure 2.

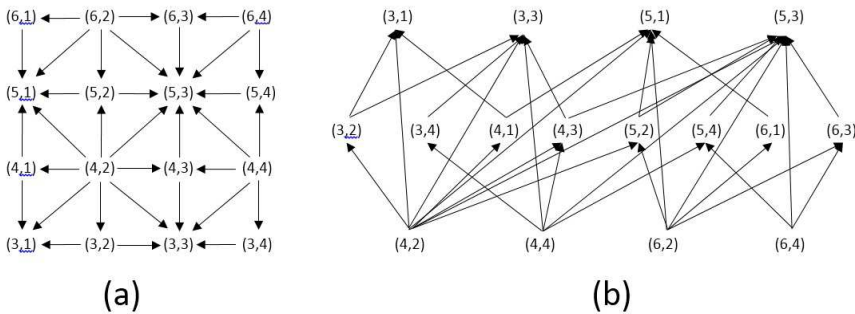


Figure 2: Part of the Hopf topology on \mathbb{Z}^2

Remark 4.9. Let (\mathbb{Z}^2, τ_s) be the Hopf topology. We describe \leq_s as follows : if $(x, y) \in OO$, then $(x, y) \leq_s (a, b)$ iff $x = a$ and $y = b$. If $(x, y) \in EE$, then

$(x, y) \leq_s (a, b)$ iff $a \in \{x - 1, x, x + 1\}$ and $b \in \{y - 1, y, y + 1\}$. If $(x, y) \in EO$, then $(x, y) \leq_s (a, b)$ iff $a \in \{x - 1, x, x + 1\}$ and $b = y$. Finally if $(x, y) \in OE$, then $(x, y) \leq_s (a, b)$ iff $a = x$ and $b \in \{y - 1, y, y + 1\}$.

Theorem 4.10. *If $A \in \{OO, EE\}$ and $B = \mathbb{Z}^2 \setminus A$, then the relative topology on B with respect to the Hopf topology is equal to the relative topology on B with respect to the Marcus-Wyse topology. That is, $(B, \leq_s |_B) = (B, \leq_m |_B)$.*

Proof. Let $A = OO$ and suppose that U is a nonempty open set in (B, τ_m) . Let $x \in U$. If $x \in EE$, then $(\uparrow_s x) \cap B = N_4(x) = (\uparrow_m x) \cap B \subseteq U$. If $x \in EO \cup OE$, then $(\uparrow_s x) \cap B = \{x\} = (\uparrow_m x) \cap B \subseteq U$. Thus, U is open in (B, τ_s) and $\tau_m|_B \subseteq \tau_s|_B$. Similarly we prove $\tau_s|_B \subseteq \tau_m|_B$. Hence $\tau_m|_B = \tau_s|_B$. Let $A = EE$. It suffices to note that the relative topology on B with respect to the τ_s^d is equal to dual relative topology on B with respect to τ_s . \square

Theorem 4.11. *Let \mathbb{Z}^2 be the Hopf space, then:*

- (1) \mathbb{Z}^2 is a semi- T_2 -space.
- (2) \mathbb{Z}^2 is not submaximal space and hence it is not a $T_{\frac{1}{4}}$ -space.

Proof. (1) For any $x = (a, b) \in \mathbb{Z}^2 \setminus OO$, we have $|\hat{x}| \geq 2$. Then by Theorem 1.6, \mathbb{Z}^2 is a semi- T_2 -space.

- (2) Direct from Theorem 1.3. \square

5. Applications of Digital Topologies on \mathbb{Z}^2

Let $\mathbb{F}_0^1 = \{\{a\} : a \in \mathbb{Z}\}$ and $\mathbb{F}_1^1 = \{\{a, a + 1\} : a \in \mathbb{Z}\}$. Let $f \subseteq \mathbb{Z}^2$. For $n = 0, 1, 2$, if f is a cartesian product of n elements of \mathbb{F}_1^1 and $2 - n$ elements of \mathbb{F}_0^1 , we say that f is a *an n -face* or simply a face of \mathbb{Z}^2 , n is the *dimension* of f , and we write $\dim(f) = n$. The *space of cubical complexes* \mathbb{F}^2 is the set composed of all faces of \mathbb{Z}^2 . We denote by \mathbb{F}_k^2 ($0 \leq k \leq 2$) the set composed of all k -faces of \mathbb{Z}^2 . Clearly that $\mathbb{F}_k^2 \subseteq \mathbb{F}^2$. The couple $(\mathbb{F}^2, \subseteq)$ is a poset.

Thus there is a corresponding T_o -Alexandroff space $(\mathbb{F}^2, \tau_{\subseteq})$. Indeed this topology is called the *cellular-complex topology* for the digital plane introduced by Alexandroff and Hopf (1935). Let $F \subseteq \mathbb{F}^2$ be a set of faces, and let $f \in F$ be a face. Then the face f is a *facet* of F if f is a maximal in F . Actually, if $x = (x_1, x_2) \in \mathbb{Z}^2$, the set $\dot{x} = \prod_{i=1}^2 \{x_i, x_i + 1\}$ is a facet of \mathbb{F}^2 and x is called the *leader* of \dot{x} and we write $L(\dot{x}) = x$ in Mazo (2012). Let $\mathbb{F}_{\{0,2\}}^2 = \mathbb{F}_0^2 \cup \mathbb{F}_2^2$.

Definition 5.1. *The Marcus-Wyse function $\kappa : \mathbb{F}_{\{0,2\}}^2 \longrightarrow \mathbb{Z}^2$ is a bijection function define as :*

$$\kappa(f) = \begin{cases} (a+b, a-b), & \text{if } \dim(f) = 0 \text{ and } f = \{(a, b)\}; \\ (a+b+1, a-b), & \text{if } \dim(f) = 2 \text{ and } L(f) = (a, b). \end{cases}$$

Definition 5.2. *The 2-Alexandroff Hopf function $\psi_2 : \mathbb{F}^2 \longrightarrow \mathbb{Z}^2$ is a bijection function define as:*

$$\psi_2(f) = \begin{cases} (2a, 2b), & \text{if } \dim(f) = 0 \text{ and } f = \{(a, b)\}; \\ (2a+1, 2b), & \text{if } \dim(f) = 1 \text{ and } f = \{a, a + 1\} \times \{b\}; \\ (2a, 2b+1), & \text{if } \dim(f) = 1 \text{ and } f = \{a\} \times \{b, b + 1\}; \\ (2a+1, 2b+1), & \text{if } \dim(f) = 2 \text{ and } f = \{a, a + 1\} \times \{b, b + 1\}. \end{cases}$$

Using the 2-Alexandroff Hopf function and Theorem 1.2, we have the two following theorems :

Theorem 5.3. *The Hopf topology (\mathbb{Z}^2, τ_s) is homeomorphic to the cellular-complex topology $(\mathbb{F}^2, \tau_{\subseteq})$.*

Theorem 5.4. *Let (\mathbb{Z}^2, τ_m) be the Marcus-Wyse topology on \mathbb{Z}^2 , then (\mathbb{Z}^2, τ_m) is homeomorphic to $(\mathbb{F}_{\{0,2\}}^2, \tau_{\subseteq})$.*

6. Conclusion

In this paper we proved there are two topologies on \mathbb{Z}^2 that are satisfying the two conditions 1², 2² which are the Hopf and the Marcus-Wyse Topologies. We studied their properties. We hope this study will be a facilitating component of the study of Digital Topology and its applications through our findings about the minimal neighbourhoods of this topologies and represent them graphically.

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